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Poultry Farm Using Sensor Technologies in Their Operations

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Annotation: Hands-on management is the norm in most henhouses. Air quality, temperature, and humidity are only a few environmental characteristics that must be properly maintained. Each of these factors affects poultry production. There is a much higher mortality rate among broiler chickens than the normal rate. Using IoT and Wireless Sensor Networks, this research hopes to improve the health of Brunei's chickens by reducing the mortality rate and increasing the number of healthy chicks that can be produced (WSN). Prototypes developed using IoT and WSN technologies were used to verify the above parameters against thresholds. Autocorrection operations are triggered whenever one or more of these parameters cross a predetermined threshold. Additionally, the user is alerted through SMS when something goes wrong with the system. These metrics can also be tracked and displayed via a Web interface.

Keywords: Poultry Farm, Using Sensor, Technologies, Operations, automatic alert notification.

Introduction:

Both meat and eggs are nutrient-dense. They're eaten for their protein and mineral content. Due to rising demand, chicken farming is one of India's most important agricultural industries [1]. This project emphasizes layer chicken growth [2]. Layer hens lay eggs. Temperature, air quality, humidity, food, and water must guarantee healthy chicken growth. The suggested initiative attempts to boost India's production by automating monitoring the above elements and cultivating poultry feed using the Internet of Things (IoT) [3].

Objective

The main objective of our project is to

- > To reduce the mortality rate of chicken
- ➤ Less manpower
- > To produce a healthy chicken

Its methods allow for remote monitoring and control of chickens from afar. Environmental monitoring and control are critical and require study in agriculture and biology [4-11]. According to a global survey, chicken is a popular food crop. In terms of nutrition, it's rich in protein, low in fat and cholesterol, and requires little effort to consume. Increasing consumer knowledge of the safety of food products like chickens and growing demand for high-quality chicken food have occurred in recent years [12-22]. Through remote sensing, wireless sensors and mobile networks are linked together in this study. Broiler hens aged 49 to 63 days are affected by the temperature-humidity index [23]. The temperature in the coop has an impact on both the productivity and living performance of the chickens housed there [24-37]. High ventilation rates are required for heavy

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broilers (more than 3.2 kg) to keep them warm and productive. Large birds pant in mild to moderate temperatures, suggesting that the highest temperature threshold is lower for heavier birds [38]. These, or temperature-humidity indices, integrate the two variables. There is a possibility that the heat could affect performance. In this investigation, heavy broilers were kept at dry-bulb temperatures of 15°C, 21°C, and 27°C, as well as relative humidity levels of 50, 65, and 80 percent. Monitoring and automation of chicken farms utilizing wireless sensors and GPRS networks is the goal to control and automatically monitor environmental elements such as temperature, humidity, ammonia gas, etc., a study on smart poultry farm automation and monitoring system incorporated wireless sensors and GPRS network [39-45]. Users may be sent a text message about chicken farms' internal environmental conditions. The system responds to a sudden change in the climate by regulating environmental elements. Food and water levels are monitored using sensors. Poultry farms' environmental records are available for review online. It was decided to use the low-power, high-performance Raspberry Pi processor. The LM35 temperature, SY-HS-220 Humidity, and MQ135 sensors detect Ammonia Gas in the air. The water level is measured using an MQ Smoke Sensor and a Level Sensor. Sensors are shown in the diagram below as being used to link automation devices in a chicken farm [46-67].

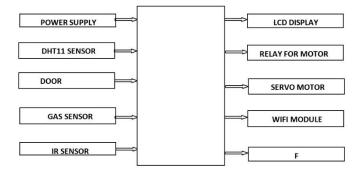


Figure 1: Block Diagram

Block diagram showing (figure 1) sensor and Arduino poultry farm automation [68]. This provides a high-level overview of system components, process participants, and working connections. The graphic below depicts how sensors connect poultry farm automation equipment. Circuit schematics design, build, and maintain electronics. This diagram demonstrates a sensor-based automated poultry farm [69-75].

Working Principle

A temperature sensor will automatically turn on a fan or heater. A DHT11 sensor can accurately measure indoor temperatures [76-89]. The microprocessor turns on the exhaust fan or heater depending on whether the chicken coop needs cooling or heating. It provides comfortable, energy-efficient conditions for cattle without manual monitoring. The DHT11 sensor determines whether to humidify or dehumidify the chicken coop. When the DHT11 sensor's humidity is below the threshold, a steam-producing electric jug humidifies the poultry house. When humidity is high, the exhaust fan turns on [90]. The fan removes unnecessary dampness. Crowding away from heat sources and flailing wings frequently indicate high temperatures [91-115].

Proposed System

The suggested system sends IoT data. A wireless Sensor Network (WSN) consists of spatially distributed autonomous devices employing sensors to monitor physical or environmental factors, such as temperature and humidity [116-122]. The sensor measures environmental temperature. The

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humidity sensor estimates air temperature, while the Gas sensor detects gas. IoT receives all info. Network nodes communicate wirelessly. Each node may sense, process, and broadcast data to neighboring nodes or the base station [123]. LCDs controller status. In this article, fire protection and anti-theft elements assure farm surveillance. Data storage through IoT is another appealing feature of this technology, allowing users to determine the necessary preset before any threats materialize. This increases agricultural productivity and produces healthy poultry [124-131].

Pin Diagram

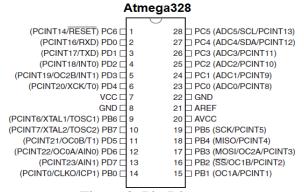


Figure 2: Pin Diagram

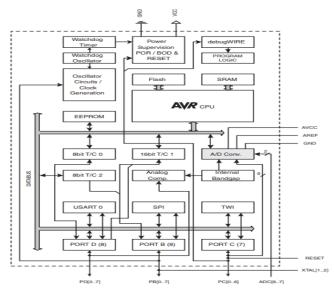


Figure 3: Architecture Diagram

The AVR has separate programs, data memory, and buses to maximize performance and parallelism (figures 2 and 3). Single-level pipelining executes program memory instructions [132-141]. This idea executes instructions per clock cycle. Programming memory is reprogrammable flash. Controls Unit 32x8 GPR Bus ALU Data 8-bit SRAM SPI Instruction Decoder Stopwatch ADC EEPROM I/Os Control Lines I/O Module Straightforward Redirect Program Counter Flash Program Memory I/O Module 2. ALU can also do single-register operations. The status register is updated after an arithmetic operation [147].

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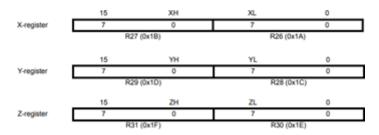


Figure 4: Arithmetic operation

Jump and call instructions directly (figure 4) address the entire addresses space to control programme flow. AVR instructions are 16-bit words. Every programme memory address is 16- or 32-bit. Boot programme and application programme parts split programme flash memory. During interruptions and subroutine calls, the stack stores the PC. SP is writable in I/O space. AVR's five addressing modes make data SRAM easy to reach [148-167]. AVR's memory areas are linear and regular. The stack stores temporary data, local variables, and procedure return addresses. The stack grows from top to bottom. The stack pointer register always points up. The stack pointer points to the Subroutine and interrupts stacks in SRAM [168-171].

Power Supply

USB or external power can power the Arduino Uno. Automatically chooses power source. An ACto-DC adapter (wall-wart) or battery can provide external (non-USB) power. The board may be unstable if less than 7V is given to the 5V pin. Using more than 12V may destroy the board's voltage regulator [172-185]. 7-12 volts is preferable. Power pins: VIN. Arduino's external power input voltage (as opposed to 5 volts from the USB connection or other regulated power source). The onboard regulator produces 3.3 V. 50 mA is the max current. GND Electrodes. Sleep modes allow applications to power down unneeded MCU modules. The AVR's sleep modes let you adapt power consumption to your application. When activated, BOD checks power supply voltage during sleep times [186-191].

General Purpose Input and Output

Using pin Mode (), digital Write (), and digital Read (), each of Uno's 14 digital pins can be utilized as an input or output. 5 volts. Each pin may deliver or receive 40 mA and contains a 20-50 KOhm pull-up resistor (disconnected by default). Some pins are specialized. RX0 and RX1 (TX). TTL serial data RX and TX [192-195]. These pins connect to ATmega8U2 USB-to-TTL Serial chip pins. Two external interruptions. These pins might trigger an interrupt on a low value, rising or falling edge, or value change. Details are in Interrupt (). PWM 3,5,6,9,10,11 analogWrite () produces 8-bit PWM. (SS), (MOSI), (MISO), (13). (SCK). These pins provide SPI communication, which is given by the hardware but not an Arduino [196]. 13-LED Pin 13 has an integrated LED. LED is on when the pin is HIGH; off when low. The Uno has 6 analog inputs with 10-bit resolution (i.e., 1024 different values). They measure from ground to 5 volts by default, although the AREF pin and analog Reference() function can adjust this. Some pins are specialized.

DHT11 Sensor

This DHT11 Temperature and Humidity Sensor provides a calibrated digital signal output. This sensor has a resistive element and a wet NTC sensor [197-199]. It's high-quality, quick, and anti-interference. Each DHT11 sensor's humidity chamber is accurate. The single-wire serial interface system is simplified. Small size, low power, and 20-meter signal transmission distance enable numerous applications (figure 5).

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Figure 5: DHT11 sensor

DHT11 sensor reads temperature and humidity. DHT11's analog output is connected to Arduino A0's analog input. 3-pin dht11 sensor. The dht11 sensor also calculates dew point, heat index, etc. High humidity requires this. High humidity causes this. Hair's humidity level. High humidity causes sweating.

4.3.4 IR SENSOR IR LEDTransmitter

Infrared LEDs emit infrared light. IR light's wavelength (700nm – 1mm) is higher than visible light's. IR LEDs offer a 20-60-degree light-emitting angle and a range of approx. IR transmitter type and manufacturer determine range. Kilometer-range transmitters exist. Photoreceptor When light lands on a photodiode, it conducts IR. The photodiode is a P-N junction semiconductor that operates in Reverse Bias when light hits it. Light affects current flow. This allows IR detection. The photodiode has a black covering like an LED; black absorbs light most. Preset Variable Resistor It calibrates the detection range (figure 6).

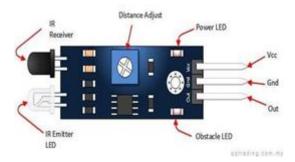


Figure 6: IR sensor

Gas Sensor

MQ-135 Gas sensors detect or measure NH3, NOx, Alcohol, Benzene, Smoke, and CO2 in air quality control systems. The MQ-135 sensor module's Digital Pin makes it work without a microprocessor. This helps when detecting one gas (figure 7).



Figure 7: Gas sensor

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DC Water Pump

Micro Submersible Pump 3-6V DIY little water pump for a garden fountain. This tiny Submersible Pump Motor runs on 3 6V. Connect the tube to the motor outlet, submerge it, and power it. Motorized pumps use 6,12,24 or 32 volts DC. A basic gear drive powers the impeller in a sealed container (figure 8).



Figure 8: DC Water Pump

Relay Board

Electromechanical relays have coils. A little current via the coil creates a magnetic field that moves, closes, or opens the switch. A relay controls a high-voltage (AC or DC) circuit using a tiny DC circuit without any direct electrical connection (figure 9).

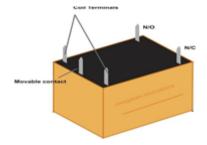


Figure 9: Relay

Operations of Relay

A small DC energizes the relay coil. The armature is attracted to the NO pin. When the coil current stops, the armature returns to its usual position, connecting COM to NC (Normally Connected). All fundamental relays operate similarly (figure 10).

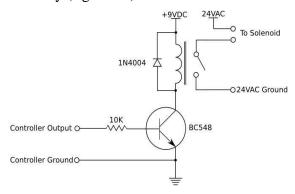


Figure 10: Circuit Diagram of relay

Selecting Your Servo Motor

Each servo motor has you can prefer a 0° to 360° motor or modify the motor to form a full circle. If your application requires stronger and longer-running motors, choose metal or plastic gears (figure 11).

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Figure 11: Servo motor

Next is the motor's torque. At 0.5cm, the engine can pull 5kg; at 2cm, only 1.25. The project's load determines the motor's torque.

How To Use A Servo Motor

Then comes the matter of how to use the Servo motor. This motor has three wires. This page's top describes it. To rotate this motor, we must supply +5V via the Red and Brown wires and PWM via the Orange wire (figure 12).

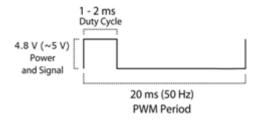


Figure 12: Servo motor with PWM period

50Hz PWM signal, 20ms time. On-Time is 1ms to 2ms. When the on-time is 1ms, the motor is at 0° , 1.5ms, 90° , and 2ms, 180° .

LCD Display

Hobbyists employ many displays. LCDs are their most advanced display device. Once you interface it, it'll be your easiest and most reliable output device. Debuggers aren't always usable for microcontroller-based projects. LCDs can test outputs. LCDs block light. Electrical currents arrange liquid crystal molecules, allowing light to pass through and form colors and images. A liquid crystal display's backlight illuminates rectangular pixels.

Wi-Fi Module

It can also get online data through API, making your app smarter. This module may be programmed using Arduino IDE, making it user-friendly. This module version has just 2 GPIO pins (you may hack it to utilize up to 4). Thus, you must use it with another microcontroller like Arduino; otherwise, choose the ESP-12 or ESP-32 variants (figure 13).

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Figure 13: Wi-Fi Module

Buzzer

Mechanical, electromechanical, or piezoelectric buzzers are auditory signaling devices. Alarms, timers, and user input confirmation use buzzers. Mechanical, electromechanical, or piezoelectric buzzers are auditory signaling devices. Buzzers and beepers are used as alarms, timers, and user input confirmations (mouse click, keystroke). DC voltage produces single-tone sound. Future Electronics has several common types: Sound Level, Frequency, Rated Voltage, Dimension, and Packaging Type (figure 14).



Figure 14: Buzzer

Result

A cooling fan and light generate a more stable temperature (about 32 degrees Celsius) than without them, promoting healthy hens. Using a fan and light generates more consistent relative humidity (about 60%) than without them. This makes barn chickens healthier. Assume good hygiene, food, and water are also maintained. In that instance, reducing chicken farm mortality will boost output (figure 15).



Figure 15: Output image

Conclusions

The climate on the farm influences the health of the hens and the farm employees. Hens might

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suffer from digestive, respiratory, and other health issues due to poor climatic circumstances. Environment control is challenging in Brunei because of the country's tropical climate. IoT and mobile technology in Brunei poultry farms can enhance the climate and reduce mortality. Data analytics can be used to predict bird diseases like bird flu and others that can have devastating effects on the poultry farm eco-system to help the farm owner take corrective action before it happens. A sleep-and-wake mode can be used in the smart chicken coop to save energy. An automated extinguisher system can be implemented at a future date. We can submit chicken vaccine remnants, worker information, and so on on the internet. A food preserver and a playhouse employ the same technology.

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